

Grid-connected inverter design and production







Overview

What is the control design of a grid connected inverter?

The control design of this type of inverter may be challenging as several algorithms are required to run the inverter. This reference design uses the C2000 microcontroller (MCU) family of devices to implement control of a grid connected inverter with output current control.

What is a grid-connected inverter?

In the grid-connected inverter, the associated well-known variations can be classified in the unknown changing loads, distribution network uncertainties, and variations on the demanded reactive and active powers of the connected grid.

What is a grid-connected solar microinverter system?

A high-level block diagram of a grid-connected solar microinverter system is shown in Figure 4. The term, "microinverter", refers to a solar PV system comprised of a single low-power inverter module for each PV panel.

Can grid-connected PV inverters improve utility grid stability?

Grid-connected PV inverters have traditionally been thought as active power sources with an emphasis on maximizing power extraction from the PV modules. While maximizing power transfer remains a top priority, utility grid stability is now widely acknowledged to benefit from several auxiliary services that grid-connected PV inverters may offer.

Does an inverter meet grid standards?

As aforementioned, the inverter is interconnected to the grid, so it should fulfill the grid standards as well. These standards includes power quality, grid ride through capability and islanding prevention. Power quality is mainly measured on the basis of Power Factor (PF) and Total Harmonic Distortion (THD).



How is a grid-connected inverter system simulated?

The test system is described shown in Fig. 13.6, the grid-connected inverter system is simulated using Matlab/Simulink. The simulation model mainly includes the main circuit module and the control module of a three-phase two-level inverter. The grid-connected inverter can distribute the active and reactive power according to the control.



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Strategy I has better transients in frequency, output current, and power. Strategy I reaches steady state faster with overshoots and has a



tracking error in the reactive power. Strategy II has





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